

WEST Search History

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side by side	<i>DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
L2	(autonomous\$2 or articulat\$4 or self-control\$3) and L1 (robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and ("on-line" or Internet or Ethernet or elecronic\$4 or computer\$4 or remote\$2) (sales or transact\$4 or business or vend\$3)	244	L2
L1		4125	L1

END OF SEARCH HISTORY

[◀ Back to Previous Page](#)**Virtual space decision support system (VSDSS) and the production/sales unification system applied to it***Imamura, K.; Nomura, J.; Ohata, H.; Schultz, R.J.;*

Robot and Human Communication, 1992. Proceedings., IEEE International Workshop on , 1-3 Sep 1992

Page(s): 263 -268

Trends in acoustic velocity log technology at RD Instruments*Young, J.; Rowe, F.; Brumley, B.; Bradley, S.;*

Autonomous Underwater Vehicles, 1998. AUV'98. Proceedings Of The 1998 Workshop on , 20-21 Aug 1998

Page(s): 89 -101

Object turning for barcode search*Rembold, D.; Belogrougov, V.; Worn, H.;*

Intelligent Robots and Systems, 2000. (IROS 2000). Proceedings. 2000 IEEE/RSJ International Conference on , Volume: 2 , 2000

Page(s): 1267 -1272 vol.2

Time optimal robot navigation via the slack set method*Zaharakis, S.C.; Guez, A.;*

Systems, Man and Cybernetics, IEEE Transactions on , Volume: 20 Issue: 6 , Nov/Dec 1990

Page(s): 1396 -1407

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robot "on-line sales" autonomous

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